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1. Introduction

The Model 2145 Time-to-Amplitude Converter/SCA generates a rectangular output pulse whose peak amplitude is linearly proportional to the time interval between a START and STOP input pulse pair. The built-in Time Single Channel Analyzer, COINCidence/ANTICOINCidence gating, RESET, STOP INHIBIT features enhance the Model 2145’s flexibility for your nuclear timing analysis needs.

The basic time-to-amplitude conversion (TAC) analyzes the time relationships between random events, such as nuclear decay, that occur within a selected interval of time. The Model 2145 is ideal for time of flight, positron lifetime, pulse shape analysis in particle studies, and pulse pair timing in position sensitive detector systems.

To meet these needs, the Model 2145 offers 15 time ranges from 20 ns to 1 ms, with a jumper selectable time offset extending the useful range of the two shortest time ranges. The positive unipolar TAC output is essentially flat topped for accurate measurement by an ADC.

Internal gating prevents a TAC output pulse for overrange START to STOP time differences, STOP inputs received prior to an accepted START, and START or STOP signals received during the converter busy time. The front panel OVERRANGE, VALID CONVERSION and BUSY LEDs simplify setup of the instrument. The COINCidence/ANTICOINCidence gating feature permits prompt (early) gating of a START/STOP pulse pair and is best used to minimize conversion time on unwanted pulses.

The single channel analyzer (SCA) portion of the Model 2145 operates on the TAC output pulse amplitude, and places equivalent timing restriction on the time spectrum being accumulated. For a selected TIME RANGE, a 0 to 100% time window can be selected with the front panel TIME and ΔTIME ten-turn locking-dial potentiometers.

An SCA logic output is produced for every TAC pulse whose peak amplitude falls between the TIME setting and the sum of TIME plus ΔTIME settings. A front panel SCA IN/OUT switch lets the TAC output be gated by the SCA output, or be generated normally.

Both the TAC and SCA outputs are simultaneously adjustable in width (internal jumper plug for 0.5, 1.0, or 2.5 μs) and are synchronous, so timing jitter on the SCA output is essentially non-existent. The front panel DELAY allows selection of the delay between the receipt of a STOP signal and the generation of an output signal.
Following a valid conversion, the STROBE function allows an external control signal to determine if and when a TAC output is generated. The start and duration set the time window during which a strobe signal will be accepted. They are controlled by the DELAY and CONV READY signals respectively. In the EXT STROBE Mode, the DELAY and CONV READY signals allow minimization of system dead time.

VALID START and VALID STOP outputs represent the time interval from the accepted START or STOP until TAC reset occurs. The front panel STOP INHIBIT adjustment allows rejection of STOP input signals in a range of 1% to 100% of each time range. This is useful for suppressing unwanted inputs in applications such as linear accelerators, and prevents false outputs. A MONITOR output is provided; when its output is true, STOP pulses are inhibited.

The RESET/INHIBIT input permits late anticoincidence gating. It is used to terminate a conversion cycle and prevent subsequent conversions while driven. For example, it can prevent a TAC output based on slow energy analysis.

The VALID START, VALID STOP, SCA, CONV READY, and MONITOR outputs are each internally selectable as positive voltage pulses or negative fast NIM current pulses. Each positive output is source matched with a 50 ohm series resistive termination, preventing ringing on unterminated cables, which can cause multiple counting.
2. Controls and Connectors

Front Panel

This is a brief description of the 2145’s front panel controls and connectors. For more detailed information, refer to Appendix A, Specifications.

Figure 1 Front Panel
Internal Controls

Figure 2 shows the location of 2145’s internal jumpers. For detailed information, refer to Appendix A, Specifications.

The jumpers should be set to your specific requirements before applying power to the module. Access to the jumpers is obtained by removing the unit’s left side cover.

Figure 2 Internal Controls
3. Operation

This section outlines the operation of the Model 2145 TAC/SCA. Following these procedures will make you familiar enough with the instrument to be able to use it effectively in any situation.

Installation

The Canberra Model 2000 Bin and Power Supply, or equivalent, will accommodate the Model 2145. The right side cover of the two-width NIM module acts as a guide for insertion of the instrument. The module is secured in place by turning the two front-panel captive screws clockwise until finger tight. It is recommended that the NIM bin power switch be OFF whenever the module is installed or removed.

The Model 2145 can be safely operated where the ambient air temperature is between 0 and 50 °C (120 °F, maximum). Perforations at the top and bottom of the unit permit cooling air to circulate through the module. When rack mounted along with other heat generating equipment, adequate clearance should be provided to allow for sufficient air flow through both the perforated top and bottom covers of the NIM bin.

Initial Setup

If you want to use the internal controls in other than their default settings (Figure 2), you should remove the left side cover of the instrument and set the internal jumper plugs to provide the desired input and output characteristics. Canberra recommends that you make these selections with the 2145’s power OFF.

INPUTS: The polarity of the START, STOP, GATE, STROBE and RESET input signals is selected by jumper plugs. Since most fast timing discriminators provide a negative output, these jumpers are shipped in the negative position and should be changed only if the input signal is positive.

Since reflection-induced ringing can cause timing degradation, both polarities of the START, STOP and GATE inputs are terminated in 50 ohms.

The input circuits for STROBE and RESET/INHIBIT each accept positive voltage or negative current NIM pulses without the need for polarity selection switches. The input impedance for the negative current pulse is 50 ohms. The input impedance for the positive voltage pulse is 1 kilohm. If it is necessary to decrease the impedance at the STROBE or RESET inputs in order to minimize reflection induced ringing, an external 50 ohm terminator can be connected to the input BNC. Ringing can be caused by fast rise time signal sources or long cable lengths.
Outputs
The VALID START, VALID STOP, SCA, MONITOR, and VALID CONVERSION outputs each may be selected individually to provide a positive voltage or a negative current NIM pulse. The positive voltage pulse output provides a 50 ohm nominal source impedance to prevent ringing and pulse reflections, which can cause spurious effects or multiple pulse counting. The negative current pulse output is shunt terminated in 50 ohms nominal for the same reason.

You can select the positive voltage pulse by setting the appropriate jumper near the identified output to +, and the negative current output by setting the jumper to –.

Width
The TAC output pulse may be set for a nominal width (at the 50% level) of 0.5, 1.0, or 2.5 µs to accommodate the pulse requirements of the ADC being used. In each case, the rise time of the output pulse is controlled to 0.25 ps to prevent slew-rate induced errors in the peak detector of the ADC. You should set the WIDTH jumper plug to the desired pulse width.

Note: The SCA output pulse (either positive or negative) will have the same width as the TAC output as selected above.

Output Impedance
The output impedance of the TAC output may be selected as either 10 ohms or 93 ohms. Use 10 ohms for driving short lengths of cable connected to an MCA. For long cable runs or when source matching is desired, use 93 ohms. The TAC is designed to generate a full scale 10 V output when fed into a high input impedance which is characteristic of many MCA's including Canberra's. To drive ADC's with 50 ohm inputs, it is recommended that the 2145's output impedance be set at 93 ohms. This will preserve linear operation of the 2145, although the output voltage will be reduced.

Valid Conversion
The width of the Valid Conversion signal which is available at the CONVERSION READY output is adjustable using a front panel potentiometer. The Valid Conversion jumper plug selects the adjustment range, either 2 to 20 ps or 20 to 200 µs.

Offset
In order to extend the linearity of the 2145 when extremely short time measurements are being made, a voltage equivalent to approximately 5 ns is subtracted from each output pulse when the OFFSET jumper is set to the ON position. This jumper affects only the 20 ns and 50 ns time scales.
The OFFSET feature is useful when making very short measurements within those ranges. If necessary, a 5 ns delay cable can be inserted at the STOP input to cancel the effect of the offset while preserving the extra range gained by using the OFFSET feature.

**Bin Voltage**

If the 2145 is being used in a NIM BIN equipped with ±6 V power supplies, the BIN VOLTAGE jumper should be set to the 6 V position to take advantage of the the NIM Bin's 6 V capability. If ±6 V is not available from your BIN, set the jumper to the 12 V position.

Once the internal jumper plugs have been set to provide the input/output characteristics desired, you should make external cable connections to the instrument to set up a familiarization test. Again, these connections should normally be done with power OFF.

**Verifying Proper Operation**

The most straightforward method to verify proper operation and/or calibration of the Model 2145 Time Analyzer is to apply a known fixed-frequency pulse to both the START and STOP inputs and to observe the amplitude of the TAC output. As illustrated in Figure 3, a pulse waveform (either positive or negative) is applied to the STOP inputs. A slightly longer coax cable and T-connector link the START and STOP inputs together.

The input signal should be adjusted to deliver $\geq 2$ V if using positive signals, and $\geq -800$ mV for negative signals.
Note: With START and STOP linked together, the net input impedance will be reduced to as low as 25 ohms in this demonstration, and will attenuate a pulse generator's normal output. Since the START signal is delayed by the extra cable length, the STOP signal arrives first and is ignored. Thus, a START signal and the STOP signal one cycle later generate a conversion time equal to the period of the input signal.

For a reference condition, a 1 MHz pulse with a width of up to 0.5 µs, or a suitable square wave from a laboratory function generator, may be used initially. It is suggested that the Model 2145 be configured as follows:

**Internal Jumpers**
- START, STOP, GATE as needed for input signal
- LOGIC OUTPUT POLARITY set for negative output
- OUTPUT WIDTH to 1 ps
- OUTPUT IMPEDANCE to 10 ohms
- VALID CONVERSION INTERVAL to 1–20 µs range

**Front Panel**
- TIME RANGE to 20 ns *MULTIPLIER to X100
- COI NC/ANTI to ANTI
- STOP INHIBIT to OFF
- DELAY to MIN
- STROBE MODE to INT
- SCA ON/OFF to OFF

Given the above setup, you should see a TAC output pulse of 5 V peak amplitude on an oscilloscope (Figure 4). The VALID CONVERSION LED will be lit. A change in the frequency (rate) of the applied input will then result in a proportional change in the amplitude of the TAC output. By reducing the rate to approximately 0.45 MHz (2.2 µs period), the user may verify that the TAC output disappears and the front panel OVERRANGE indicator will come on.

Note: The BUSY LED will be green when no input is applied. It will become more red as the input frequency is increased and the module spends more and more time processing pulses.
Using the SCA Functions

Note: Because of the internal analog and logic propagation delays of the Model 2145, a cable about 10 feet (3 m) in length should be used between the tee connector and the START input to obtain a useful TAC output using this setup.

At this point you can examine the VALID START, VALID STOP, and SCA output pulses in either + or – modes (see “Using the SCA Functions”, below). In Figure 5, a 2:1, 50 ohm attenuator is connected to one of the oscilloscope inputs. This attenuator will preserve pulse fidelity which may otherwise be degraded by oscilloscope input capacitance. When using the positive logic outputs of the 2145, the attenuator at the oscilloscope input is not necessary and the input impedance at the oscilloscope input should be set to 1 megohm.

Using the SCA Functions

The Time Single Channel Analyzer function is most commonly used to restrict the spectrum of pulse pairs received by the instrument to a narrow range of most interest in a given experiment. These may represent specific coincidences from several detectors, particle disintegrations, annihilations, lifetimes, etc. The Time SCA function evaluates the result of a given time-to-amplitude conversion and generates a logic output for input time differences within the bounds set by the front panel controls.
Figure 5 illustrates positive and negative SCA output pulses using the prescribed terminations. Figure 6 illustrates the aberrations caused by ungrounded oscilloscope probes (top) and oscilloscope input capacitance (bottom).
Using the SCA Functions

The Time Single Channel Analyzer function is most commonly used to restrict the spectrum of pulse pairs received by the instrument to a narrow range of greatest interest in a given experiment. These may represent specific coincidences from several detectors, particle disintegrations, annihilations, lifetimes, etc. The Time SCA function evaluates the result of a given time-to-amplitude conversion and generates a logic output for input time differences within the bounds set by the front panel controls.

The TIME control on the front panel sets the lower limit for the SCA region or window, as scaled from 0 to 100% of any selected time range. The TIME control sets the width of the SCA window over the same 0 to 100% range, so that the upper limit of time is read as the sum of the TIME and $\Delta$TIME dial settings.

The logic output decision of the SCA function may be used to gate the TAC output so that only those pulses within the set SCA limits will be delivered to an external ADC for analysis. This is done by setting the front panel SCA ON/SCA OFF switch to SCA ON. When this switch is set to SCA OFF, all outputs will be delivered to the ADC.

Note: The VALID CONVERSION indicator is not affected by the SCA on/off switch because that indicator shows only if the inputs are within the TIME RANGE and MULTIPLIER switch settings.

Using the settings on page 8, but with SCA ON, the front panel TIME control set to 2.0 and the $\Delta$TIME control to 6.0, an oscilloscope observation of the TAC output will be seen only for pulses between 2.0 and 8.0 V as the input test frequency is varied up and down.

Figure 7 shows the Model 2145's differential nonlinearity as observed on a Canberra MCA using random noise pulses to generate a time spectrum on the 20 x100 ns range, and with the SCA set as above. The sharp skirts of the spectrum attest to the precision of the SCA built into the Model 2145.
Using the Stop Inhibit Function

It is possible in some experiments to have STOP pulses that are caused or contaminated by noise or pulse reflections. If these unacceptable STOP pulses are not rejected in some way, they will initiate unintended time analysis cycles, contribute to the Time Analyzer's dead time, and thus affect the high throughput qualities of the Model 2145.

Why not use the self-contained Time SCA to reject these STOP pulses? By creating a time window which would restrict the TAC output to acceptable pulse pairs the noise pulses could be kept from generating a TAC output. However, this would still incur increased dead time and possibly block time analysis on a desired START/STOP pair.

The STOP INHIBIT function has been designed to overcome this limitation by setting a "time threshold" just before an acceptable STOP pulse. The Time Analyzer will not recognize STOP pulses which are below this threshold.

By careful adjustment of the STOP INHIBIT control, unacceptable (early) STOP input pulses can be suppressed, reducing excessive Time Analyzer dead time and the generation of false TAC outputs. As an aid in setting the Inhibit threshold, the MONITOR output BNC provides a logic pulse whose width is equal to the blocking time interval following an accepted START input pulse.

Figure 8 illustrates the effect of a STOP INHIBIT set at approximately 10% of the 1 µs range of the Model 2145, as seen on a flat time spectrum using random pulser inputs.
Using the Coincidence Function

The most common use of the Coincidence function is for early (prompt) gating of START/STOP pulse pairs as an aid in reduction of the Time Analyzer's dead time. Since the internal logic of the Analyzer is set to reject any STOP pulses that arrive before an accepted START pulse, a means of accepting or rejecting a START pulse will allow the operator to control pulse pair conversion.

By selecting one of the two modes of gating and applying a specified signal to the GATE connector, the operator can enable or disable the acceptance of a START pulse, and thus the conversion of any pulse pairs.

In the COINCidence mode, an applied GATE signal will enable the operator to select a START pulse for beginning a conversion cycle. Only START pulses coincident with the GATE pulse are allowed to initiate a conversion. Pulse pairs that are not coincident will not be processed by the Analyzer.

In the ANTICOINCidence mode, conversions will be inhibited for START pulses coincident with the GATE signal. All other pulse pairs will be converted.

In either mode, an applied GATE signal will affect acceptance of a START pulse if the GATE signal is received at least 10 ns prior to the START pulse and overlaps the START pulse by approximately 50 ns.

Note: If the Coincidence function is not to be used, the mode switch must be left in the ANTICOINCidence position and the GATE input must be left open.
Using the Strobe Function

The Strobe function allows external logic to determine whether and when a TAC output is generated. This occurs after the TAC conversion and reduces ADC dead time by preventing undesired TAC outputs. Figure 9 shows timing diagrams, illustrating the use of the Strobe function.

When the Strobe Mode switch is set to INTernal, the TAC functions normally. After the DELAY period, every conversion produces a TAC output pulse.

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Figure 9  Timing Relationships of TAC Signals
In the EXTernal Strobe Mode, an external Strobe signal must be applied during the VALID CONVERSION interval to produce a TAC output pulse. This interval starts at the end of DELAY and has a width determined by the front panel CONV READY WIDTH potentiometer and the internal VALID CONVERSION INTERVAL jumper.

If a Strobe signal is applied during the VALID CONVERSION interval, a TAC output pulse will be generated immediately. If the Strobe signal is absent during the VALID CONVERSION interval, the TAC is reset at the end of VALID conversion and no output pulse is generated.

**Operation in a System**

The 2145 can be operated with either synchronous or random inputs. When synchronous inputs are present, start/stop time intervals may all be within the VALID CONVERSION time range shown by the front panel indicator. With random inputs however, such as those generated by a radioactive source, the start/stop time intervals may be random in which case both the VALID CONVERSION and OVER RANGE indicators will be lit.

In some cases it may be advantageous to exchange the START and STOP inputs. This is often done if the start (excitation) rate is much higher than the stop (response) rate. To minimize the dead time of the 2145 in this situation the input representing the response can be connected to the START input and the input representing the excitation can be delayed and connected to the STOP input. The delay is picked to equal the time range of interest as set on the front panel.

The spectrum obtained from this setup will be inverted, with events representing short excitation/response time intervals appearing at the high end of the spectrum, since the time measured by the 2145 is now the excitation/response interval subtracted from the delay time. Dead time, which can be monitored with the BUSY indicator, is now minimized, since the STOP input circuit will ignore stop inputs received during processing time.
4. Circuit Description

The Model 2145 Time to Amplitude Converter (TAC) is shown in block diagram form in Figure 10. The basic time to amplitude converter consists of an integrator which operates by charging a capacitor with a constant current during the time interval from a START signal to a STOP signal. The current linearly charges the capacitor, producing a ramp voltage. The charging process stops when the STOP signal is received. The voltage present on the capacitor is linearly proportional to the START to STOP time interval.

The other portions of the circuitry shown in the block diagram serve to interface the time to amplitude integrator circuit to the inputs and outputs of the TAC or to provide various other logic or control functions. The input circuits and the latches generate signals which control the switches associated with the integrating capacitor and the current source. The capacitor buffer is a high input impedance, low output impedance circuit which provides drive capability to the output linear gate and amplifier as well as the various comparators for the OVERRANGE, SCA, and MONITOR functions. The control logic generates control signals which activate various portions of the circuit sequentially during each conversion.
Input signals are applied to the START, STOP, and GATE input circuits. All three circuits are substantially the same. Each consists of a high speed comparator with the capability of responding to a positive or negative NIM input signal with the polarity chosen by the position of the input jumper. When a suitable input occurs, the comparator output changes state and provides a logic signal to drive the inputs of the latches that follow. The input circuits are very fast and are limited in count rate primarily by the width of the input signal. This allows high count rate signals to be applied directly to the TAC input, with no timing degradation.

The START and STOP input circuits drive the clock inputs of high speed ECL D-type latches. The GATE input circuit drives the D input of the START latch and is able to provide fast COINCIDENCE/ANTICOINCIDENCE gating. The second START latch output drives the D input of the second STOP latch and ensures that STOP signals prior to a START signal are signal rejected. The STOP INHIBIT signal drives the D input of the first stop latch to prevent unwanted stop commands from being recognized. After level shifting, the outputs from the START and STOP latches are used to directly control the current source which charges the integrating capacitor and the FET which resets the ramp voltage to zero.

In order to provide the 2145’s various RANGE and MULTIPLIER settings, both the current source and the integrating capacitor are variable. The current source, consisting of the operational amplifier A2 and transistor Q2B is varied with the front panel RANGE switch to provide the 20, 50, and 100 RANGE settings. Likewise the integration capacitor, consisting primarily of C23, C12, C13 or C14, is chosen with the front panel MULTIPLIER switch.

Prior to a conversion, the integrating capacitor is clamped at a quiescent voltage level determined by the current through source Q15C and the on resistance of clamp FET Q6C. At the start of the conversion, the clamp transistor (Q18) is turned off by a logic signal from the START latch, thus steering the source current to the integrating capacitor. This results in a positive going ramp on the integrating capacitor. When a STOP signal is received, the current from source Q2B is steered away from the integrating capacitor by Q15B which turns on as Q15C turns off. The integrating capacitor retains the charge it received during the conversion. The charge deposited on the integrating capacitor is the product of the charging current and the start/stop time interval, resulting in a fixed voltage which represents the time interval converted.

Transistors Q25, Q26 and Q27 form a buffer which provides a high impedance load on the integrating capacitor. This avoids discharging the integrating capacitor while providing drive capabilities to the output circuitry and comparators which follow the buffer.
Transconductance amplifier A6 and associated circuitry monitor the output of buffer Q5 and set it to zero volts after the integrating cap is reset. This circuitry compensates for the quiescent voltage developed across clamp FET Q6C and the offset of emitter follower Q5. C37 is used as a memory element to store the voltage level necessary to cancel the offsets. In order to keep the dc level on C37 from being affected by the ramp signal, amplifier A6 switches off during the start/stop interval. When the OFFSET jumper is in the ON position, an offset voltage equivalent to approximately 5 ns is subtracted from the buffer output.

Transistors Q3A, Q3B, Q3C and Q3D form a gate which opens to read out the final ramp level just after the start/stop interval has ended. The gate feeds A4, which together with Q9 and Q10 form the output amplifier whose gain is two. Thus a full scale conversion generates 5 V on the integrating capacitor and 10 V at the output. The duration of the output pulse is determined by the length of time the gate is opened.

A conversion is considered valid if a STOP signal is received during the conversion interval. A valid STOP signal initiates the output sequence controlled by the string of logic one-shots A13A, A13B, A12B and A16A for DELAY, VALID CONVERSION, OUTPUT, and RESET, respectively.

After a valid conversion, an output signal is generated by the OUTPUT one-shot and the entire circuit is RESET. This clears the logic, clamps the integrating capacitor, and prepares the circuit for the next conversion. If no STROBE signal appears during the VALID CONVERSION interval or if an OVERRANGE is detected, the circuit is RESET without generating an output.

Several comparators monitor the output of the buffer: the OVERRANGE comparator, the two SCA comparators, and the STOP INHIBIT comparator. The OVERRANGE comparator detects an overrange condition if the ramp exceeds 5 V. If this occurs, the converter circuitry is reset without generating an output. The two SCA comparators determine if the conversion is within the range set by the Lower Level and Upper Level controls. The STOP INHIBIT comparator determines when a selected percentage of the conversion range has been exceeded and allows STOP inputs to be accepted after this point if this function is enabled.

A lower limit time cutoff determined by RV8 and C164 is set to reject start/stop intervals less than approximately 5 ns. Since these short intervals are still within the time range setting the LED indicators are not affected.

Five logic outputs are provided by the 2145: the VALID START, VALID STOP, SCA, CONVERSION READY, and STOP INHIBIT MONITOR outputs. All are identical and consist of a positive NIM voltage driver and a negative NIM current driver. The desired output polarity is selected by a jumper plug.
A. Specifications

Inputs

START – Accepts negative or positive logic signals or levels, internally selected; shipped in negative position. Negative threshold ~250 mV; positive threshold 1 V; width ≥2 ns. Z_{in} ≈ 50 Ω, selectable to ≈ 1 kΩ by removal of internal resistor; dc coupled input protected to ±10 V. Leading edge initiates time conversion.

STOP – Input specifications identical to START input. Leading edge terminates time conversion.

GATE – Input specifications identical to START input. Gates TAC output in either COINCidence or ANTICOINCidence mode. GATE must begin 10 ns prior to and overlap START input.

STROBE – Input voltage requirements identical to START input; width ≥50 ns; Z_{in} = 1 kΩ for positive signals, 50 Ω for negative signals, dc coupled; initiates output pulse when in EXT strobe mode; must occur in time window set by CONV READY.

RESET/INHIB – Input specifications identical to strobe input; serves as a late anticoincidence input and terminates conversion cycle. The reset period ends at the conclusion of RESET/INHIB or the internal clear time, whichever occurs last.

Outputs

TAC – Provides positive flat topped rectangular unipolar pulse; constant pulse shape independent of TIME RANGE or amplitude; amplitude proportional to accepted START/STOP input pulse time difference; adjustable delay (0.5 to 10.5 μs) and width (0.5, 1.0 or 2.5 μs); rise time ≈ 250 ns; dc coupled; front panel BNC connector. Z_{out} = 10 Ω or 93 Ω, internally selectable. Shipped set for 10 Ω and 1 ms width; 10 V full scale into high impedance load.

VALID START (converter busy time) – Provides either TTL compatible positive voltage pulse with T_{rise} and T_{fall} <25 ns, or ~16 mA current pulse with T_{rise} <10 ns; shipped in negative position; Z_{out} = 50 Ω, dc coupled; duration equal to time interval between accepted START input and end of cycle reset time.

VALID STOP – Output pulse specifications identical to VALID START; duration equal to time interval between accepted STOP input signal and end of cycle reset time.
SCA – Output pulse specifications identical to VALID START; leading edge is in time coincidence with, and duration is equal to, TAC output.

STOP INHIBIT MONITOR – Output pulse specifications identical to VALID START; monitors STOP INHIBIT RANGE adjustment.

CONVersion READY – Output pulse specification identical to VALID START. Active from end of DELAY period. Duration set by CONV READY WIDTH control. Range set by internal jumper, 1 to 20 μs or 10 to 200 μs; shipped in 1–20 μs position. Indicates period when STROBE input will initiate output pulse.

Front Panel Controls
TIME RANGE – Three-position rotary switch selects full scale time interval of 20, 50, or 100 ns between accepted START and STOP input pulses.

MULTIPLIER – Five-position rotary switch extends TIME RANGE by X1, X10, X100, X1K or X10K.

DELAY – 22-turn screwdriver potentiometer varies TAC output delay time; 0.5 to 10.5 μs range, with adjacent toggle switch in VARiable; fixed 150 ns relative to STOP input with switch in MINimum. Test point monitors the DELAY time setting.

GATE MODE – Toggle switch selects COINCidence or ANTICOINCidence gating. Time conversion is enabled (COINC) or inhibited (ANTICOINC) upon receipt of a GATE input signal.

TIME – 10-turn locking dial potentiometer selects minimum time of interest from 0 to 100% of selected TIME RANGE.

Δ TIME – 10-turn locking dial potentiometer selects time window width from 0 to 100% of selected TIME RANGE.

SCA IN/OUT – Toggle switch selects whether TAC output is gated with Time SCA.

STROBE MODE – Toggle switch selects INTernal or EXTernal strobe operation.

CONVersion READY WIDTH – 22-turn, screwdriver adjustable potentiometer determines time duration during which STROBE input will initiate output pulse; jumper selectable for 1 to 20 μs or 10 to 200 μs, shipped set for 1 to 20 μs.

STOP INHIBIT – Toggle switch enables (ON) or disables (OFF) STOP INHIBIT RANGE adjustment.
Internal Controls

STOP INHIBIT RANGE – 22-turn potentiometer to reject unwanted STOP input signals from 1% (minimum 20 ns) to 100% of selected TIME RANGE.

TAC OUTPUT WIDTH – Jumper selects 0.5, 1.0 or 2.5 µs output pulse width for both SCA and TAC outputs.

TAC OUTPUT IMPEDANCE – Jumper selects $Z_{out} = 10 \, \Omega$ or 93 Ω.

START +/-, STOP +/-, GATE +/-, STROBE +/-, RESET +/-: Jumpers determine input polarity of respective signals.

VALID START +/-, VALID STOP +/-, SCA +/-, STOP INHIBIT +/-, CONVERSION READY +/-: Jumpers select either positive voltage or negative current mode outputs for the respective signals.

CONV READY – Jumper selects 1 to 20 µs or 10 to 200 µs range.

OFFSET ON/OFF – Jumper enables (ON) or disables (OFF) output time offset, extending usable range by $\approx 5$ ns when TIME RANGE is set to 20 ns or 50 ns. Shipped in ON position.

BIN VOLTAGE – Jumper configures 2145 for Bins with 6 V power supply.

Indicators

OVERRANGE – Glows red when START/STOP time interval exceeds selected range.

VALID CONVERSION – Red LED lights when START/STOP time interval and gating produce a TAC output. Not affected by SCA setting.

BUSY – Bicolor LED is green when TAC is inactive, turns red to indicate significant count rate.

Performance

TIME RESOLUTION – <0.01% of full scale plus 5 ps FWHM.
TAC DIFFERENTIAL NONLINEARITY – With OFFSET jumper set to ON, typically ≤±1% (maximum 2%) from lower limit of useable range to full scale. For 20 ns TIME RANGE, lower limit is 5 ns; for all other TIME RANGES, lower limit is 10 ns or 1% of full scale, whichever is greater.

TAC INTEGRAL NONLINEARITY – With OFFSET jumper set to ON, <±0.1% over useable range, as described in Differential Nonlinearity specification.

SCA TIME/Δ TIME INTEGRAL NONLINEARITY – <±0.5% of full scale.

TAC OUTPUT TEMPERATURE STABILITY – >±0.01%/°C (±100 ppm/°C) of full scale, plus 10 ps/°C.

SCA TIME/Δ TIME TEMPERATURE STABILITY – >±0.01%/°C (±100 ppm/°C) of full scale.

OUTPUT DELAY/OUTPUT WIDTH TEMPERATURE STABILITY – >±0.01%/°C (±100 ppm/°C) of full scale.

TEMPERATURE OPERATING RANGE – 0 to 50 °C.

TAC OUTPUT DROOP – <0.015%/µs of delay from completed conversion to TAC output. Delay time is determined by front panel DELAY setting or external strobe acceptance, or both.

CONVERTER RESET – 1µs for X1 and X10 multipliers, 5 µs for X100, 40 µs for X1K and X10K; occurs after TAC output, reset or overrange.

GATE PEDESTAL – Essentially zero pedestal, factory calibrated.

SCA OUTPUT TIME WALK – None, with respect to TAC output.

MINIMUM START TO STOP CONVERSION TIME – ≈ 2 ns.

COUNT RATE CAPABILITY – START, STOP, GATE inputs capable of count rates greater than 25.

Connectors

All signal connectors are front panel BNCs.
Power Requirements

**Power Requirements**

\[+24 \text{ V dc} \text{ – 70 mA}\]  \[+12 \text{ V dc} \text{ – 230 mA}\]

\[–24 \text{ V dc} \text{ – 30 mA}\]  \[–12 \text{ V dc} \text{ – 290 mA}\]

**Physical**

SIZE – Standard double-width NIM module 6.85 x 22.12 cm (2.70 x 8.71 in.) per DOE/ER-0457T.

NET WEIGHT – 1.3 kg (2.8 lb).

SHIPPING WEIGHT – 2.3 kg (5.0 lb).
B. Installation Considerations

This unit complies with all applicable European Union requirements.

Compliance testing was performed with application configurations commonly used for this module; i.e. a CE compliant NIM Bin and Power Supply with additional CE compliant application-specific NIM were racked in a floor cabinet to support the module under test.

During the design and assembly of the module, reasonable precautions were taken by the manufacturer to minimize the effects of RFI and EMC on the system. However, care should be taken to maintain full compliance. These considerations include:

- A rack or tabletop enclosure fully closed on all sides with rear door access
- Single point external cable access
- Blank panels to cover open front panel Bin area
- Compliant grounding and safety precautions for any internal power distribution
- The use of CE compliant accessories such as fans, UPS, etc.

Any repairs or maintenance should be performed by a qualified Canberra service representative. Failure to use exact replacement components, or failure to reassemble the unit as delivered, may affect the unit’s compliance with the specified EU requirements.
Canberra (we, us, our) warrants to the customer (you, your) that for a period of ninety (90) days from the date of shipment, software provided by us in connection with equipment manufactured by us shall operate in accordance with applicable specifications when used with equipment manufactured by us and that the media on which the software is provided shall be free from defects. We also warrant that (A) equipment manufactured by us shall be free from defects in materials and workmanship for a period of one (1) year from the date of shipment of such equipment, and (B) services performed by us in connection with such equipment, such as site supervision and installation services relating to the equipment, shall be free from defects for a period of one (1) year from the date of performance of such services.

If defects in materials or workmanship are discovered within the applicable warranty period as set forth above, we shall, at our option and cost, (A) in the case of defective software or equipment, either repair or replace the software or equipment, or (B) in the case of defective services, reperform such services.

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We are under no obligation to provide warranty service if adjustment or repair is required because of damage caused by other than ordinary use or if the equipment is serviced or repaired, or if an attempt is made to service or repair the equipment, by other than our Service Personnel without our prior approval.

Our warranty does not cover detector damage due to neutrons or heavy charged particles. Failure of beryllium, carbon composite, or polymer windows, or of windowless detectors caused by physical or chemical damage from the environment is not covered by warranty.

We are not responsible for damage sustained in transit. You should examine shipments upon receipt for evidence of damage caused in transit. If damage is found, notify us and the carrier immediately. Keep all packages, materials and documents, including the freight bill, invoice and packing list.

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