

z_*OBSOLETE* Conversion to .mat

***** OBSOLETE, DO NOT USE *****

CRITICAL UPDATE: Use new **XMLab** software for marker-based XROMM, including Undistortion, Calibration, Marker Tracking, and Rigid Bodies.

XMLab replaces XrayProject. See [Bitbucket XMLab wiki](#) for XMLab User Manual (not this wiki).

Convert the undistortion to the MATLAB format

Note: You have to do this for each camera

1. Make sure you have the ConvertCSVAndPointsToLUT program in your Matlab path
 2. Type ConvertCSVAndPointsToLUT in the Matlab command line
 3. Click the button
 4. Select the “_UNDSTFORM.csv” file
 5. Select the “_INPTS.csv” file
 6. Select the “_BSPTS.csv” file
 7. Select where you want the .mat file to be saved
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[Workflow Diagrams](#)